### Line Integrals

Let C be a smooth, <u>oriented</u> (<u>directed</u>) curve in space.  $\vec{F}$ is a continuous vector field. Approximate C by a collection of small line segments (directed) { $\Delta \vec{r_i}$ }. Consider the sum  $\sum_i \vec{F}(\xi_i) \cdot \Delta \vec{r_i}$  where  $\xi_i$  is a point on the line segment  $\Delta \vec{r_i}$  (the concept of <u>work</u>), then take the limit  $|\Delta r_i| \to 0$ 

$$\sum_{i} \vec{F}(\xi_{i}) \cdot \triangle \vec{r}_{i} \quad \rightarrow \quad \int_{C} \vec{F} \cdot d\vec{r}$$

This is called the line integral of  $\vec{F}$  over C.

If C is not smooth but is <u>piecewise smooth</u>, composed of smooth curves  $C_1, C_2, \dots C_n$ , then

$$\int_{C} \vec{F} \cdot d\vec{r} = \sum_{i=1}^{n} \int_{C_{i}} \vec{F} \cdot d\vec{r}.$$

Also, with -C defined to be the curve having the same points but opposite orientation of C,

$$\int_{-C} \vec{F} \cdot d\vec{r} = -\int_{C} \vec{F} \cdot d\vec{r}.$$

As  $\vec{F} = F_1 \vec{i} + F_2 \vec{j} + F_3 \vec{k}$  and  $d\vec{r} = dx\vec{i} + dy\vec{j} + dz\vec{k}$ , another form to write a line integral is

$$\int_{C} \vec{F} \cdot d\vec{r} = \int_{C} F_1 dx + F_2 dy + F_3 dz.$$

### Evaluation of Line Integrals

Let  $\vec{r}(t) = x(t)\vec{i} + y(t)\vec{j} + z(t)\vec{k}$  be a parameterization of C with domain [a, b], and assume that the <u>parameterization induces</u> the given <u>orientation</u> (direction) of C. Then (the formula for evaluation)

$$\int_{C} \vec{F} \cdot d\vec{r} = \int_{a}^{b} \vec{F} \circ \vec{r}(t) \cdot \frac{d\vec{r}}{dt} dt.$$

- Example A particle moves upward along the circular helix C, parameterized by  $\vec{r}(t) = \cos t \vec{i} + \sin t \vec{j} + t \vec{k}$  for  $0 \le t \le 2\pi$  under a force given by  $\vec{F}(x, y, z) = -zy\vec{i} + zx\vec{j} + xy\vec{k}$ . Find the work done on the particle by the force (i.e. the line integral).  $2\pi^2$
- Example Assume that the particle in the previous example moves under the same force and with the same initial and terminal points,

but along the line segment  $C_2$  parameterized by

$$\vec{r}(t) = \vec{i} + t\vec{k}$$
 for  $0 \le t \le 2\pi$ .

Find the work done on the particle by the force.  $_{0}$ 

Note that 
$$\int_{C_1} \neq \int_{C_2}$$

The Fundamental Theorem of Line Integrals

<u>Theorem</u> Let C be an oriented curve with initial point  $(x_0, y_0, z_0)$  and terminal point  $(x_1, y_1, z_1)$ . Let f be a function of three variables that is differentiable at every point on C, and assume that  $\nabla f$  is continuous on C. Then

$$\int_{C} \vec{\nabla} f \cdot d\vec{r} = f(x_1, y_1, z_1) - f(x_0, y_0, z_0)$$

pf: Use Chain Rule.

Example Let C be the straight line segment from (0,2,0) to (1,0,0) and  $\vec{F}$  be the electric field of a point charge q at the origin. Find the work done by  $\vec{F}$  on a <u>unit</u> point charge that traverses C.

## Path Independence

<u>Definition</u> If a vector field  $\vec{F}$  has the property that  $\int_{C_1} \vec{F} \cdot d\vec{r} = \int_{C_2} \vec{F} \cdot d\vec{r} \text{ for } \underline{any} \text{ two oriented}$ curves having the <u>same</u> initial and terminal points, its line integrals are called path independent.

Clearly, 
$$\vec{F} = \vec{\nabla} f \implies \int_{C} \vec{F} \cdot \vec{dr}$$
 path independent.

(Fundamental Theorem of Line Integrals)

On the other hand, if the line integrals of  $\vec{F}$  are path independent, then a potential function of  $\vec{F}$  can be found as  $f(x, y, z) = \int_C \vec{F} \cdot \vec{dr}$  where C is an arbitrary curve connecting the origin (or any fixed reference point) to (x, y, z).

Therefore, 
$$\int_{C} \vec{F} \cdot \vec{dr}$$
 path independent  $\implies \vec{F} = \vec{\nabla} f$ .  
 $pf: \vec{r}(s) = (s, y_0, z_0), \ s \in [x_0, x], \ \partial_x f(x_0, y_0, z_0) = (d/dx) \int_{x_0}^x F_1(s, y_0, z_0) ds$ 

Example Let  $\vec{F} = xy^2 \vec{i} + x^2 y \vec{j}$ . a. Evaluate the line integrals  $\int_{C_1} \vec{F} \cdot \vec{dr}$  and  $\int_{C_2} \vec{F} \cdot \vec{dr}$  where  $C_1$  consists of the line segments connecting (0,0) to  $(x_0,0)$  and  $(x_0,0)$  to  $(x_0,y_0)$ , and  $C_2$  consists of the line segments connecting (0,0) to  $(0,y_0)$ and  $(0,y_0)$  to  $(x_0,y_0)$ .  $x_0^2 y_0^2/2$ b. Find a potential function for  $\vec{F}$ .

## Important Properties of a Conservative Field

<u>Theorem</u> The following statements are equivalent:

- 1.  $\vec{F} = \vec{\nabla} f$  for some function f, i.e. conservative.
- 2.  $\int_{C} \vec{F} \cdot d\vec{r}$  is independent of path.
- 3.  $\int_{C} \vec{F} \cdot d\vec{r} = 0 \text{ for every closed loop } C.$

If the domain of  $\vec{F}$  is a region with no holes, then also

4.  $\vec{\nabla} \times \vec{F} = 0.$ 

# Green's Theorem

<u>Theorem</u> Let R be a <u>simple</u> region in the xy plane with a piecewise smooth boundary C oriented <u>counterclockwise</u>. Let  $F_1$  and  $F_2$  be functions of two variables having continuous partial derivatives on R. Then

$$\int_{C} F_1(x,y)dx + F_2(x,y)dy = \iint_{R} \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y}\right)dA$$

<u>Note</u> Writing  $\vec{F}$  as  $F_1\vec{i} + F_2\vec{j}$  and considering the situation in 3 dimensions, this equation can be expressed as

$$\int_{C} \vec{F} \cdot d\vec{r} = \iint_{R} (\vec{\nabla} \times \vec{F}) \cdot \vec{k} dA$$

Pf: It is sufficient to show that

$$\int_{C} F_2(x, y) dy = \int_{C} F_2 \vec{j} \cdot d\vec{r} = \iint_{R} \frac{\partial F_2}{\partial x} dA$$

and

$$\int_{C} F_1(x, y) dx = \int_{C} F_1 \vec{i} \cdot d\vec{r} = -\iint_{R} \frac{\partial F_1}{\partial y} dA.$$

Note that the separation is done through writing  $\vec{F} = \vec{F_1} + \vec{F_2}$  where  $\vec{F_1} = F_1 \vec{i}$  and  $\vec{F_2} = F_2 \vec{j}$ .

$$-\iint_{R} \frac{\partial F_{1}}{\partial y} dA = -\int_{a}^{b} \int_{g_{1}(x)}^{g_{2}(x)} \frac{\partial F_{1}}{\partial y} dy dx$$

$$= \int_{a}^{b} [F_1(x, g_1(x)) - F_1(x, g_2(x))] dx$$

The first term is the line integral  $\int_{C_1} F_1 \vec{i} \cdot d\vec{r}$ on the curve  $C_1$  parameterized by  $\vec{r_1}(x) = x\vec{i}+g_1(x)\vec{j}$ . The second term is  $-\int_{C_2} F_1 \vec{i} \cdot d\vec{r}$ where  $C_2$  is the curve parameterized and oriented by  $\vec{r_2}(t) = x\vec{i} + g_2(x)\vec{j}, x \in [a, b]$ .

Example Find  $\int_C -x^2 y dx + x^3 dy$  where C is the circle  $x^2 + y^2 = 4$ , oriented conterclockwise.

— Problem Set 11 —