1 Course updates

The website is up at http://www.math.ust.hk/~emarberg/Math6150F and the first homework assignment have been posted. The first assignment is due in class next Monday, 13 February.

2 Reflection groups

Let V be a vector space over the real numbers \mathbb{R} , with a bilinear form $(\cdot, \cdot) : V \times V \to \mathbb{R}$ that is both symmetric and positive definite. Recall that these properties are equivalent to requiring that (u, v) = (v, u) for all $u, v \in V$ and (v, v) > 0 if $v \in V$ is nonzero.

Two vectors $u, v \in V$ are orthogonal if (u, v) = 0.

The important thing about this setup is the following basic fact from linear algebra: if $U \subset V$ is any subspace and $U^{\perp} = \{v \in V : (u, v) = 0 \text{ for all } u \in U\}$ then U^{\perp} is also a subspace and $V = U \oplus V^{\perp}$. If U is a one-dimensional space (i.e., a line), then U^{\perp} is the hyperplane orthogonal to U.

Example. If $V = \mathbb{R}^n$ then the standard choice for (\cdot, \cdot) is given by setting $(\sum_i a_i e_i, \sum_i b_i e_i) = \sum_i a_i b_i$.

Definition. The *reflection* through a nonzero vector $\alpha \in V$ is the linear map

$$s_{\alpha}: v \mapsto v - 2\frac{(v,\alpha)}{(\alpha,\alpha)}\alpha \quad \text{for } v \in V.$$

Note that we don't have to worry about dividing by (α, α) since the form is positive definite.

Fix a nonzero vector $\alpha \in V$. To get some geometric intuition for what s_{α} does, consider the following simple facts. Each of these statements follows immediately from the definition of s_{α} .

Lemma. $s_{\alpha} = s_{c\alpha}$ for any nonzero scalar $c \in \mathbb{R}$.

Lemma. $s_{\alpha}(\alpha) = -\alpha$.

Lemma. If $v \in V$ and $(v, \alpha) = 0$ then $s_{\alpha}(v) = v$.

Thus s_{α} negates α and fixes every vector orthogonal to α . In other words, s_{α} acts on V by reflecting vectors across the hyperplane orthogonal to α .

Lemma.
$$s_{\alpha}^2 = 1$$
.

Proof. This is clear from the geometric description of s_{α} just given. Algebraically, we have $s_{\alpha}^{2}(v) = s_{\alpha}(s_{\alpha}v) = s_{\alpha}\left(v - 2\frac{(v,\alpha)}{(\alpha,\alpha)}\alpha\right) = v - \frac{2(v,\alpha)}{(\alpha,\alpha)}\alpha + \frac{2(v,\alpha)}{(\alpha,\alpha)}\alpha = v$ for all $v \in V$, so $s_{\alpha}^{2} = 1$.

Proposition. If $v, w \in V$ then $(s_{\alpha}v, s_{\alpha}w) = (v, w)$.

Proof. This statement generalizes the fact from planar geometry that reflection across a line preserves angles. Algebraically, the result follows by using bilinearity to expand

$$(s_{\alpha}v, s_{\alpha}w) = \left(v - \frac{2(v,\alpha)}{(\alpha,\alpha)}\alpha, w - \frac{2(w,\alpha)}{(\alpha,\alpha)}\alpha\right)$$

= $(v,w) - \frac{2(v,\alpha)(w,\alpha)}{(\alpha,\alpha)} - \frac{2(v,\alpha)(w,\alpha)}{(\alpha,\alpha)} + \frac{4(v,\alpha)(w,\alpha)(\alpha,\alpha)}{(\alpha,\alpha)^2} = (v,w).$

We write GL(V) for the general linear group of V, consisting of all invertible linear maps $V \to V$. The orthogonal group of V with respect to the form (\cdot, \cdot) is the group O(V) consisting of all maps $g \in GL(V)$ that preserve our bilinear form, i.e., with (gv, gw) = (v, w) for $v, w \in V$. These sets are groups with respect to composition of linear maps.

The preceding proposition amounts to saying that each reflection s_{α} belongs to O(V).

Definition. A *(finite) reflection group* is a (finite) subgroup of O(V) generated by $\{s_{\alpha} : \alpha \in X\}$ for some finite set of nonzero vectors $X \subset V \setminus \{0\}$.

The goal of the next few lectures will be to classify the finite reflections groups, that is, to describe which finite groups arise as reflection subgroups of O(V) for some choice of V and the accompanying bilinear form. It turns out, surprisingly, that such a classification is possible and nontrivial. This will afford concrete realizations of many Coxeter groups, and motivate the study of Coxeter systems in general.

Example (Dihedral groups). Let $V = \mathbb{R}^2$ with the standard bilinear form. Fix a regular *m*-gon centered at the origin. Let D_m be the set of the following linear transformations:

- (i) rotation counter-clockwise by angle $\frac{2\pi j}{m}$ for $j = 0, 1, 2, \dots, m-1$,
- (ii) reflection across one of the 2m "diagonals" of our *m*-gon (that is, across a line through the origin that either connects two opposite vertices, two midpoints of opposite sides, or a vertex to the midpoint of the opposite side).

There are *m* distinct transformations of each of these types, so $|D_m| = 2m$. One can check that D_m is a group with respect to composition: this is the group of all rigid motions of \mathbb{R}^2 that preserve our regular polygon. Moreover, D_m is a reflection group since rotation by angle $\frac{2\pi}{m}$ is a product of two diagonal reflection. (Try to visualize this for m = 5 and m = 6.) Call D_m the *dihedral group* of size 2m or the *Coxeter group of type* $I_2(m)$.

Example (Symmetric groups). Recall that S_n is the symmetric group of permutations of $[n] = \{1, 2, ..., n\}$. View S_n as a subgroup of $O(n, \mathbb{R})$, the orthogonal group of $V = \mathbb{R}^n$ with the standard form, by having $w \in S_n$ act on the standard basis $e_1, e_2, ..., e_n \in \mathbb{R}^n$ via $w(e_i) = e_{w(i)}$, and extending linearly. (Check yourself that this action preserves the standard form (\cdot, \cdot) .)

Now $w \in S_n$ corresponds to the matrix $(a_{ij})_{i,j \in [n]}$ with $a_{ij} = 1$ if j = w(i) and 0 otherwise.

Recall that $S_n = \langle s_1, s_2, \dots, s_{n-1} \rangle$ where $s_i = (i, i+1)$ transposes i and i+1.

Fact. With respect to our inclusion $S_n \hookrightarrow O(n, \mathbb{R})$, we have $s_i = s_\alpha$ for $\alpha = e_i - e_{i+1}$.

Proof. If $i \in [n-1]$ and $j \in [n]$ then

$$s_{e_i-e_{i+1}}(e_j) = e_j - \frac{2(e_i - e_{i+1}, e_j)}{(e_i - e_{i+1}, e_i - e_{i+1})} (e_i - e_{i+1}) = e_j - \delta_{i,j}(e_i - e_{i+1}) + \delta_{i+1,j}(e_i - e_{i+1}).$$

The last expression simplifies to e_i if j = i + 1, to $e_{i=1}$ if j = i, and to e_j otherwise, which is $e_{s_i(j)}$. \Box

Thus S_n is (isomorphic) to a finite reflection group: this group is the Coxeter group of type A_{n-1} .

3 Root systems

To classify reflection groups, we develop some general theory about the action of such a group on the ambient vector space. Continue to let V be a real vector space with a symmetric, positive definite, bilinear form (\cdot, \cdot) . Let $W \subset O(V)$ be a finite reflection group.

Proposition. If $w \in O(V)$ and $0 \neq \alpha \in V$ then $ws_{\alpha}w^{-1} = s_{w\alpha}$. Hence if $w, s_{\alpha} \in W$ then $s_{w\alpha} \in W$.

Proof. We have $ws_{\alpha}w^{-1}(w\alpha) = ws_{\alpha}(\alpha) = w(-\alpha) = -w\alpha = s_{w\alpha}(w\alpha)$. To show that $ws_{\alpha}w^{-1} = s_{w\alpha}$, it suffices to check that $ws_{\alpha}w^{-1}(\beta) = \beta = s_{w\alpha}(\beta)$ for all $\beta \in V$ with $(w\alpha, \beta) = 0$. But if $(w\alpha, \beta) = 0$ then

$$0 = (w\alpha, \beta) = (w^{-1}w\alpha, w^{-1}\beta) = (\alpha, w^{-1}\beta),$$

so $s_{\alpha}(w^{-1}\beta) = w^{-1}\beta$ and therefore $ws_{\alpha}w^{-1}(\beta) = \beta$.

When s is a reflection in O(V), let L_s be the line spanned by any nonzero vector $\alpha \in V$ with $s = s_{\alpha}$. Note that L_s determines s, and that we get the same line for any choice of α .

The proposition shows that W permutes the set of lines $\{L_s : s \text{ is a reflection in } W\}$. To study the structure of W, we should consider this action closely. But rather than work with lines, let's instead replace each line by a pair of opposite vectors and examine W's action on the resulting set of vectors.

This sequences of ideas motivates the following definition of the *root system* of a reflection group.

Definition. Let Φ be a finite set of nonzero vectors in V such that

(R1) $\Phi \cap \mathbb{R}\alpha = \{\alpha, -\alpha\}$ for each $\alpha \in \Phi$.

(R2) $s_{\alpha}(\beta) \in \Phi$ for all $\alpha, \beta \in \Phi$.

Call Φ a root system, and refer to its elements as roots.

If $W = \langle s_{\alpha} : \alpha \in \Phi \rangle$, then we say that W is the reflection group associated to Φ .

We have the following correspondence between finite reflection groups and root systems.

Proposition. If $W \subset O(V)$ is a finite reflection group then W is the reflection group associated to some root system Φ (though this many not be unique).

Proof. Construct Φ by including the pair of unit vectors on the line L_s for each reflection $s \in W$. This set is finite since W is finite; Φ obviously satisfies (R1); and (R2) holds by the previous proposition. \Box

Proposition. If Φ is a root system and W is its associated reflection group, then W is finite.

Proof. Let $U = \mathbb{R}$ -span $\{\alpha \in \Phi\}$ and $U^{\perp} = \{v \in V : (u, v) = 0 \text{ for all } u \in U\}$. Then for each $\alpha \in \Phi$ we have $s_{\alpha}u = u$ for all $u \in U^{\perp}$, so wu = u for all $u \in U^{\perp}$. We deduce that if $w\alpha = \alpha$ for all $\alpha \in \Phi$ then w fixes all elements of $V = U \oplus U^{\perp}$, so w = 1. Thus the homomorphism $W \to S_n$ for $n = |\Phi|$ induced by the action of W on Φ has trivial kernel so is injective, and so $|W| \leq |S_n| = n! < \infty$.

Moral: from any finite reflection group we can construct a root system, and the reflections indexed by a root system generate a finite reflection group. So we should develop some theory about root systems.

Definition. A *total order* on V is a transitive relation < such that

- (1) $\lambda < \mu$ or $\lambda = \mu$ or $\mu < \lambda$ for each $\lambda, \mu \in V$.
- (2) If $\mu < \nu$ then $\lambda + \mu < \lambda + \nu$ for each $\lambda, \mu, \nu \in V$.
- (3) If $\lambda < \mu$ then $c\lambda < c\mu$ and $-c\mu < -c\lambda$ for $\lambda, \mu \in V$ and any real number c > 0.

This list of conditions looks a little technical, but really just axiomatizes the most natural properties of the usual total order on real numbers.

With respect to a total order < on V, a vector $v \in V$ is *positive* if 0 < v. Positive vectors are preserved under sums and under products by positive scalars. An important thing to note:

Proposition. A total order < exists on V.

Proof. Let e_1, e_2, \ldots, e_n be an arbitrary basis of V. Set $\lambda < \mu$ if we have $\lambda = a_1e_1 + a_2e_2 + \cdots + a_ne_n$ and $\mu = b_1e_1 + b_2e_2 + \ldots b_ne_n$, where each $a_i, b_i \in \mathbb{R}$, and it holds that $a_j < b_j$ for some $j \in [n]$ while $a_i = b_i$ for $1 \le i < j$. Check that this relation is transitive and satisfies the axioms of a total order. \Box

We refer to the total order constructed in the preceding proof and the *lexicographic order* induced by the ordered basis e_1, e_2, \ldots, e_n .

There are several important constructions attached to a root system which depend on a choice of total order on V. The relevant definitions can seem a little unnatural, since at our current level of abstraction there is no obviously "best" total order to adopt. We will see, however, that all useful definitions depending on a choice of total order are actually independent of our choice.

Definition. Let Φ be a root system. A subset $\Pi \subset \Phi$ is a *positive system* if every $\alpha \in \Phi$ is positive (i.e., $0 < \alpha$) with respect to some total order < on V.

Proposition. If $\Pi \subset \Phi$ is a positive system then $\Phi = \Pi \sqcup -\Pi$ where \sqcup denotes disjoint union.

Proof. This follows since roots in Φ come in pairs $\{-\alpha, \alpha\}$.

Definition. A subset $\Delta \subset \Phi$ is a *simple system* if Δ is a linearly independent set of vectors and each $\alpha \in \Phi$ can be expressed as $\alpha = \sum_{\beta \in \Delta} c_{\beta}\beta$ for coefficients $c_{\beta} \in \mathbb{R}$ which are either all ≥ 0 or all ≤ 0 . Elements of a simple system are called *simple roots*.

It is not obvious that every root system contains a simple system. (Why is it obvious that every root system contains a positive system?) Nevertheless, the following is true:

Theorem. Let Φ be a root system.

- (a) If Δ is a simple system in Φ , then there is a unique positive system $\Pi \subset \Phi$ containing Δ .
- (b) Every positive system $\Pi \subset \Phi$ contains a unique simple system. Thus, simple systems always exist.

Proof. Today, we prove the first part and start the second.

- (a) The unique positive system Π containing a given simple system Δ is the one defined with respect to the lexicographic total order induced by any ordering of Δ . This positive system is uniquely characterized as the intersection $\Phi \cap \mathbb{R}^+$ -span $\{\alpha \in \Delta\}$ where $\mathbb{R}^+ = \{x \in \mathbb{R} : x \ge 0\}$.
- (b) Suppose Δ is a simple system contained in a positive system Π . Then Δ is the unique simple system in Π since Δ is the subset of roots $\lambda \in \Pi$ such that $\lambda \neq \alpha + \beta$ for all $\alpha, \beta \in \Pi$.

It remains to construct a simple system $\Delta \subset \Pi$. The idea is to let Δ be the minimal subset of Π such that each $\alpha \in \Pi$ is a nonnegative linear combination of elements of Δ . This set will be a simple system if we can show that it is linearly independent—which we will do next time!