1. The two-level four-point explicit scheme for pricing the Black-Scholes option model is given by

$$
V_{j}^{n+1}=b_{1} V_{j+1}^{n}+b_{0} V_{j}^{n}+b_{-1} V_{j-1}^{n}, j=1,2, \ldots, N, n=0,1,2, \ldots
$$

The coefficients are given by

$$
\begin{aligned}
b_{1} & =\left[\frac{\sigma^{2}}{2} \frac{\Delta \tau}{\Delta x^{2}}+\left(r-\frac{\sigma^{2}}{2}\right) \frac{\Delta \tau}{2 \Delta x}\right] e^{-r \Delta \tau} \\
b_{0} & =\left(1-\sigma^{2} \frac{\Delta \tau}{\Delta x^{2}}\right) e^{-r \Delta \tau} \\
b_{-1} & =\left[\frac{\sigma^{2}}{2} \frac{\Delta \tau}{\Delta x^{2}}-\left(r-\frac{\sigma^{2}}{2}\right) \frac{\Delta \tau}{2 \Delta x}\right] e^{-r \Delta \tau}
\end{aligned}
$$

(a) Find the restrictions on the time step $\Delta \tau$ and stepwidth $\Delta x$.
(b) An implicit scheme requires the solution of a tridiagonal system of equations at every time step. Explain in two reasons why most practitioners prefer to use an implicit scheme even with this computational complexity.
(c) Explain why the usual dynamic programming procedure cannot be applied to implicit schemes for numerical calculations of an American option model. Outline briefly the numerical procedure in an iterative scheme to resolve the difficulty.
2. Consider the down-and-out proportional step call option whose terminal payoff is defined by

$$
\exp \left(-\rho \tau_{B}^{-}\right) \max \left(S_{T}-X, 0\right)
$$

where $\rho$ is the killing rate (assuming to be constant), $X$ is the strike price, $S_{T}$ is the terminal asset price, and $\tau_{B}^{-}$is the occupation time in the knock-out region that is defined by

$$
\tau_{B}^{-}=\int_{t_{0}}^{T} \mathbf{1}_{\left\{S_{t} \leq B\right\}} d t
$$

Here, $B$ is the constant down barrier and $\mathbf{1}_{\{ } \quad$ \} is the indicator function, and $t_{0}$ is the inception time of the option. We assume the usual Black-Scholes model where the dynamics of the asset price $S_{t}$ is governed by

$$
\frac{d S_{t}}{S_{t}}=r d t+\sigma d Z_{t}
$$

where $r$ is the riskfree interest rate and $Z_{t}$ is the standard Brownian motion. The usual trinomial tree algorithm takes the form:

$$
V_{j}^{n+1}=\left[\frac{\alpha+\mu}{2} V_{j+1}^{n}+(1-\alpha) V_{j}^{n}+\frac{\alpha-\mu}{2} V_{j-1}^{n}\right] e^{-r \Delta \tau}
$$

where $e^{-r \Delta \tau}$ is the discount factor over the time interval $\Delta \tau, \mu=\left(r-\frac{\sigma^{2}}{2}\right) \frac{\Delta \tau}{\Delta x}$ and $\alpha=\frac{\sigma^{2} \Delta \tau}{\Delta x^{2}}$. How do we modify the trinomial scheme so as to incorporate the "proportional step" feature? Give an explanation to your answer.

Hint Consider the damping factor being applied over one time step $\Delta \tau$ when the asset price lies below $B$ (down region).
3. In the participating policy model, there are two state variables: $A(t)$ and $P(t)$. The dynamics of the asset $A(t)$ under a risk neutral measure $Q$ is governed by the Geometric Brownian motion:

$$
d A(t)=r A(t) d t+\sigma A(t) d W^{Q}(t)
$$

The updating of the policy account $P(t)$ is based on

$$
P\left(t^{+}\right)=P\left(t^{-}\right)+\max \left(r_{G} P\left(t^{-}\right), \alpha\left\{\left[A(t)-P\left(t^{-}\right)\right]-\gamma P\left(t^{-}\right)\right\}\right)
$$

across a fixing date $t$, where
$r_{G}$ : guaranteed rate of return
$\gamma$ : target buffet ratio
$\alpha$ : distribution ratio.
Explain in details the key procedures (interpolation and extrapolation) in the incorporation of the jump condition (crediting mechanism) across a fixing date in the finite difference scheme.

Hint Write $P\left(t^{+}\right)=\widetilde{j} \Delta P$ and $P\left(t^{-}\right)=j \Delta P$. Let $A=i \Delta A$, where $\Delta A$ is the stepwidth for $A$. Explain why

$$
\widetilde{j}=j+\max \left\{r_{G} j, \alpha\left[\left(i \frac{\Delta A}{\Delta P}-j\right)-\gamma j\right]\right\} .
$$

4. In a convertible bond, the issuer can call back the bond at call price $K$ and the holder can convert prematurely with payoff denoted by conv. Let cont denote the continuation value of holding the convertible bond.
(a) Give the financial intuition in the design of the dynamic programming procedure as given by

$$
\min (K, \max (\text { cont }, \text { conv })) .
$$

(b) Suppose the three values $K$, cont and conv at the lattice tree node has the following relative order of magnitude: $K<c o n t<c o n v$. The procedure in part (a) produces the outcome $K$ while another dynamic programming procedure:

$$
\min (\max (\text { cont }, \text { conv }), \max (K, \text { conv }))
$$

produces conv as the outcome. Explain the occurrence of such inconsistency. Which dynamic programming procedure is correct, or indeed such inconsistency does not occur under the context of pricing algorithm of convertible bond? Give justification to your answer.
5. The governing equation for pricing a defaultable coupon-paying convertible bond is given by

$$
\frac{\partial V}{\partial t}+\frac{\sigma^{2}}{2} S^{2} \frac{\partial^{2} V}{\partial S^{2}}+(r-q+h) S \frac{\partial V}{\partial S}-[r+(1-R) h] V+c(t)=0
$$

(a) Using financial interpretation (not from the above equation directly), explain why the hazard rate $h$ can be visualized as negative dividend yield.
(b) The discrete coupons are modeled by the coupon rate

$$
c(t)=\sum_{i=1}^{n} c_{i} \delta\left(t-t_{i}\right)
$$

where $c_{i}$ is the discrete coupon amount paid on the coupon date $t_{i}, i=1,2, \cdots, n$. Explain how the Dirac terms in $c(t)$ arise?
6. In the pricing model of variable annuities with guaranteed minimum withdrawal benefit, we define the surrogate unrestricted fund value process by

$$
\begin{aligned}
\mathrm{d} \widetilde{W}_{t} & =(r-\alpha) \widetilde{W}_{t} \mathrm{~d} t-G \mathrm{~d} t+\widetilde{W}_{t} \sigma \mathrm{~d} B_{t}, t>0 \\
\widetilde{W}_{0} & =w_{0}
\end{aligned}
$$

Here, $\alpha$ is the participating fee rate, $G$ is the constant withdrawal rate, $\sigma$ is the volatility and $B_{t}$ is a standard Brownian motion.
(a) Give the financial justification of the solution:

$$
\widetilde{W}_{t}=X_{t}\left(w_{0}-G \int_{0}^{t} \frac{1}{X_{u}} \mathrm{~d} u\right)
$$

where

$$
\begin{equation*}
X_{t}=e^{\left(r-\alpha+\frac{\sigma^{2}}{2}\right) t+\sigma B_{t}} \tag{3}
\end{equation*}
$$

Hint Note that $X_{0}=1$. The number of fund units is depleted continuously due to withdrawal.
(b) We observe that either $\widetilde{W}_{t}>0$ for $t \leq T$ or $\widetilde{W}_{T}$ remains negative once $W_{t}$ reaches the negative region at some earlier time prior to $T$ (see the figures below).


Show mathematically that if $\widetilde{W}_{T}>0$, then $\widetilde{W}_{t}>0$ for any $t<T$.
Hint If some units of fund remains at $T$, then the fund would not be completely depleted before $T$. Give the mathematical statement of this observation.
7. Consider the scenario where we require $n$ correlated samples from standardized (zero mean and unit variance) normal distribution with the correlation coefficient between sample $i$ and sample $j$ being $\rho_{i j}$. We first sample 3 independent random variables $x_{1}, x_{2}$ and $x_{3}$ from univariate standardized normal distribution. The required correlated samples, $\epsilon_{1}, \epsilon_{2}$ and $\epsilon_{3}$, are then computed by

$$
\begin{aligned}
\epsilon_{1} & =\alpha_{11} x_{1} \\
\epsilon_{2} & =\alpha_{21} x_{1}+\alpha_{22} x_{2} \\
\epsilon_{3} & =\alpha_{31} x_{1}+\alpha_{32} x_{2}+\alpha_{33} x_{3} .
\end{aligned}
$$

Write down the governing equations for the determination of the parameters $\alpha_{11}, \alpha_{21}, \alpha_{22}$, $\alpha_{31}, \alpha_{32}$ and $\alpha_{33}$. DO NOT SOLVE THEM!

Hint Use the following 6 relations:

$$
\begin{aligned}
& \operatorname{var}\left(\epsilon_{1}\right)=1, \operatorname{var}\left(\epsilon_{2}\right)=1, \operatorname{var}\left(\epsilon_{3}\right)=1 \\
& \operatorname{cov}\left(\epsilon_{1}, \epsilon_{2}\right)=\rho_{12}, \operatorname{cov}\left(\epsilon_{1}, \epsilon_{3}\right)=\rho_{13}, \operatorname{cov}\left(\epsilon_{2}, \epsilon_{3}\right)=\rho_{23}
\end{aligned}
$$

Alternatively, we may apply the Cholesky decomposition:

$$
M M^{T}=\Sigma
$$

where $\Sigma$ is the correlation matrix and

$$
\left(\begin{array}{l}
\epsilon_{1} \\
\epsilon_{2} \\
\epsilon_{3}
\end{array}\right)=M\left(\begin{array}{l}
x_{1} \\
x_{2} \\
x_{3}
\end{array}\right) .
$$

8. (a) Let $c_{i}$ and $\widetilde{c}_{i}$ denote the simulated call value in the $i^{\text {th }}$ simulation run in the antithetic variates method in pricing a European call option to achieve variance reduction in Monte Carlo simulation. Explain why

$$
\begin{equation*}
\operatorname{var}\left(\frac{c_{i}+\widetilde{c}_{i}}{2}\right)=\frac{1}{2}\left[\operatorname{var}\left(c_{i}\right)+\operatorname{cov}\left(c_{i}, \widetilde{c}_{i}\right)\right] . \tag{1}
\end{equation*}
$$

(b) Show that the antithetic variates method improves computational efficiency provided that

$$
\operatorname{cov}\left(c_{i}, \widetilde{c}_{i}\right)<0 .
$$

Explain why the above negative correlation property is in general valid.
9. (a) Discuss the intrinsic difficulty of applying the Monte Carlo simulation method to pricing of American style options with the early exercise right.
(b) Consider the Grant-Vora-Weeks method with regard to the numerical valuation of American options using the Monte Carlo simulation approach. Discuss how the method determines the optimal stopping rules at discrete time points?

